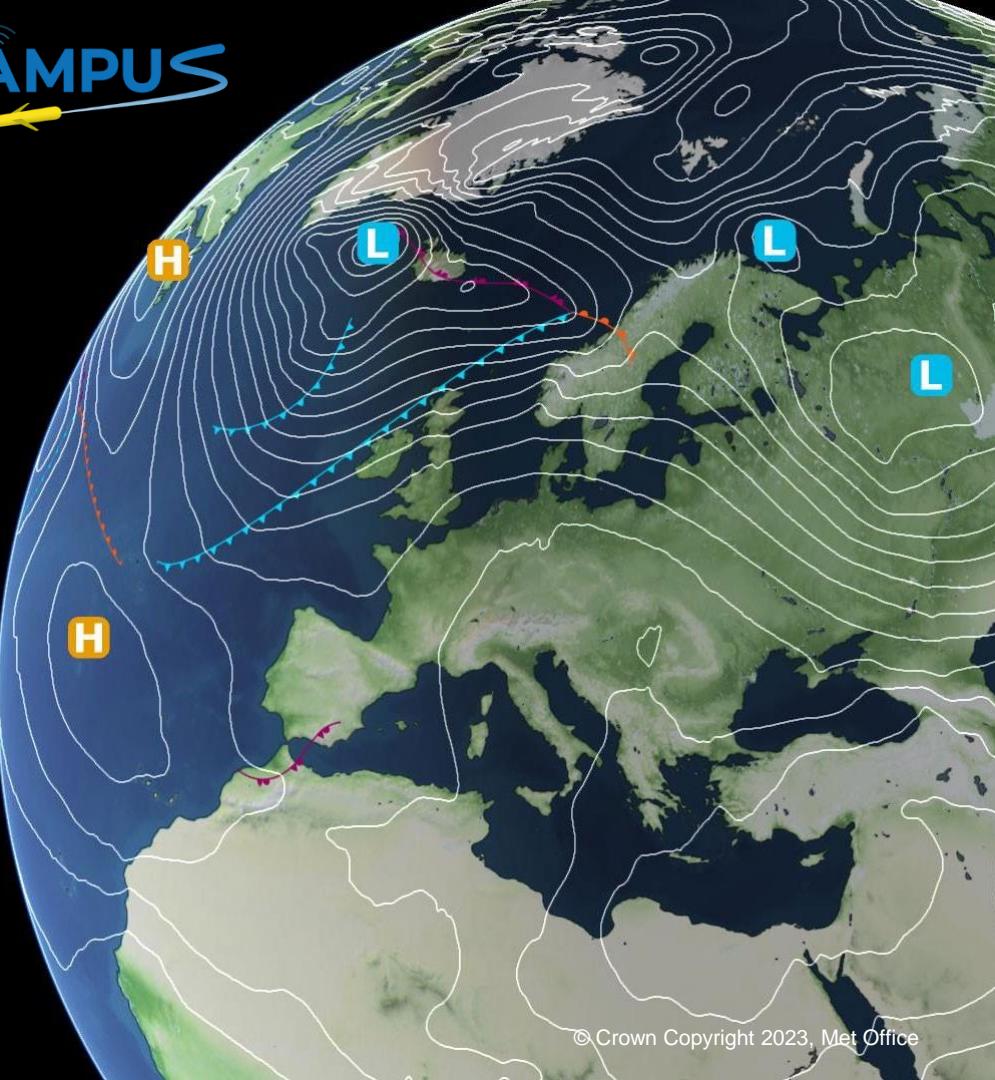


Autonomous, adaptive monitoring integrating ocean robots and operational forecasts

David Ford¹, Shenan Grossberg², Gianmario Rinaldi²,
Prathyush Menon², Matthew Palmer^{3,4}, Jozef Skákala⁴,
Tim Smyth⁴, Charlotte Williams³, Alvaro Lorenzo Lopez³,
Stefano Ciavatta⁴

¹Met Office, ²University of Exeter, ³NOC, ⁴PML

OceanPredict MEAP-TT, 3rd May 2023



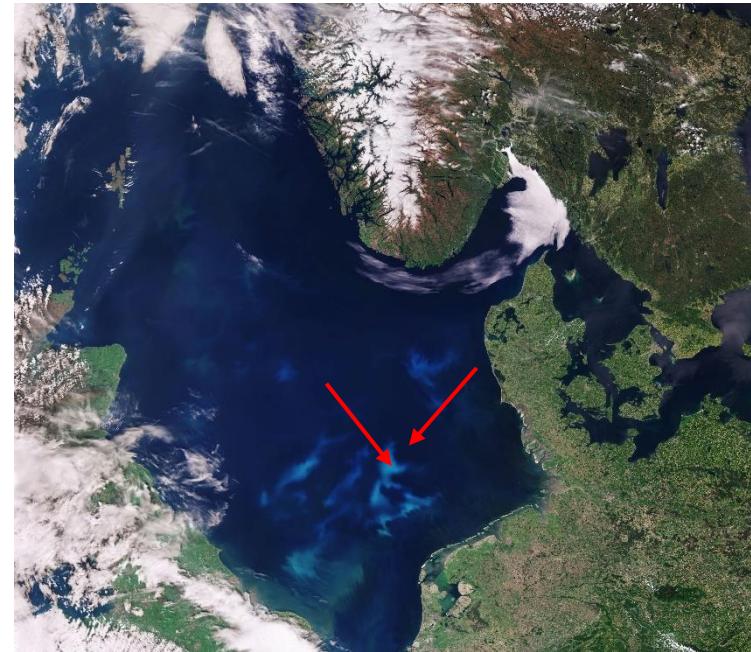
Contents

- Concept and motivation
- “Smart system”
 - Glider
 - Forecast model and data assimilation
 - Stochastic prediction model and path planning
- Results
- Summary and future challenges

Concept and motivation

Motivation

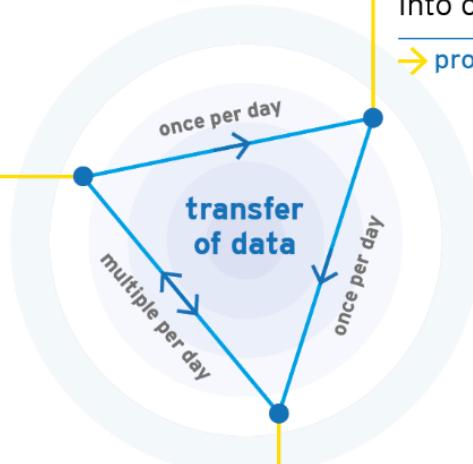
- Observations are necessary but expensive
- Want to simultaneously reduce costs and maximise impact
- Make best use of all available information (Observations! Models! Statistics!)
- Adaptive monitoring could automatically direct a robot toward a likely feature of interest (e.g. an algal bloom)



https://www.esa.int/var/esa/storage/images/esa_multimedia/images/2018/09/north_sea_bloom/17675390-1-eng-GB/North_Sea_bloom.jpg

**Glider**

Navigated by the stochastic model



Operational forecast model

Assimilate glider data
into operational model

→ produce 2-day forecast

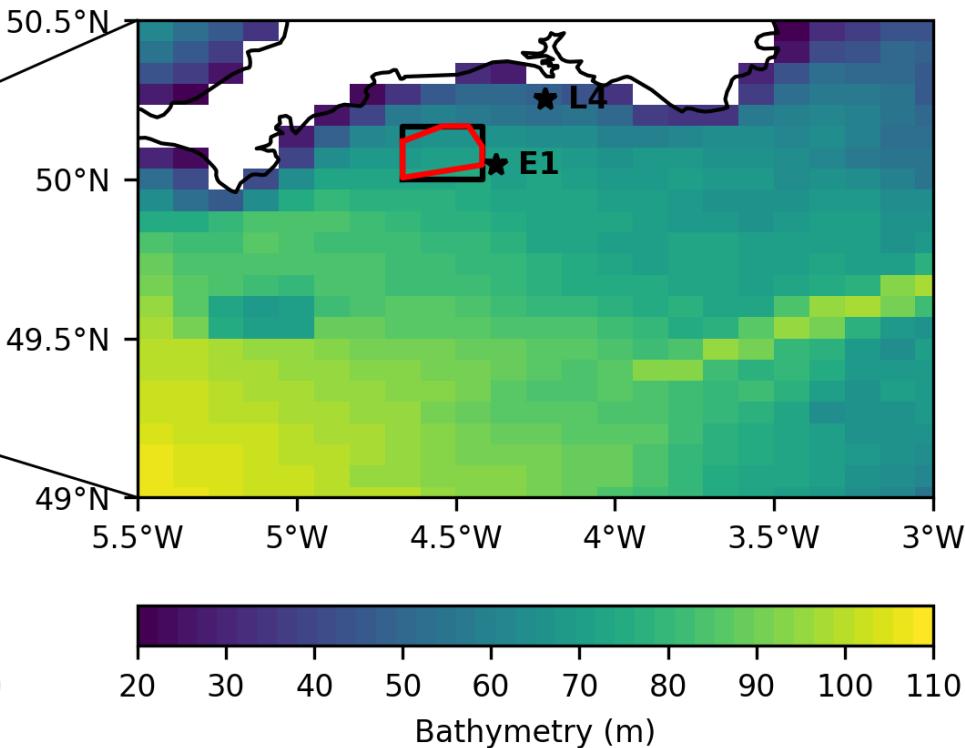
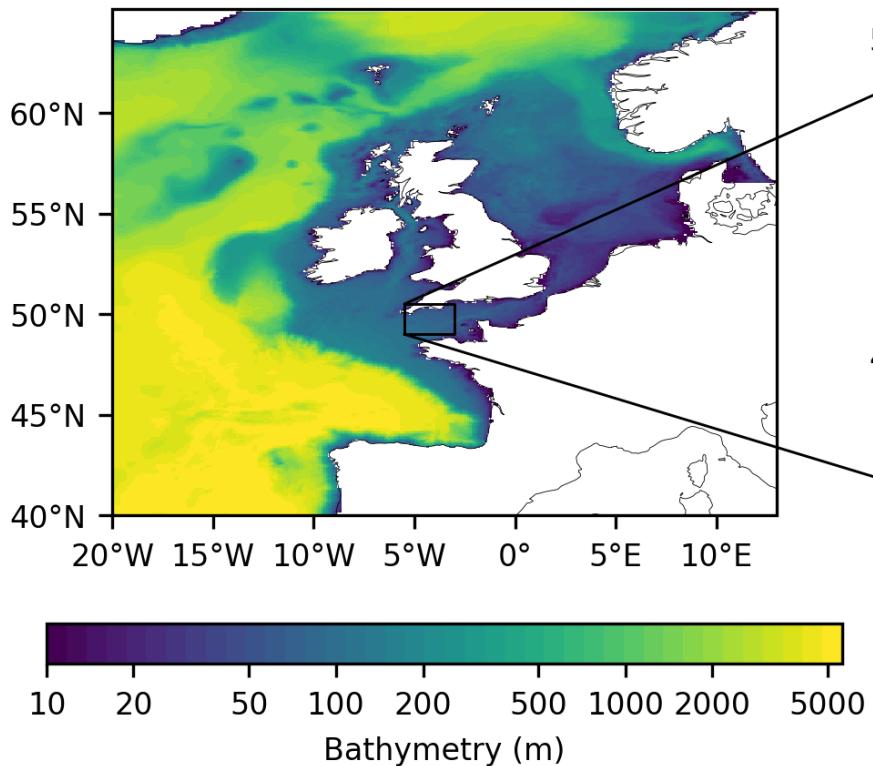


Stochastic prediction model

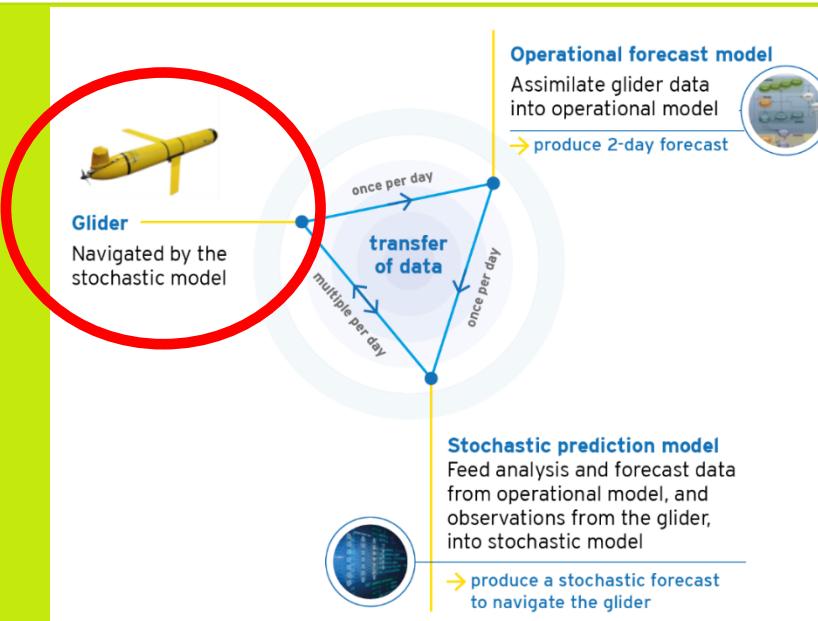
Feed analysis and forecast data
from operational model, and
observations from the glider,
into stochastic model

→ produce a stochastic forecast
to navigate the glider

22 March – 8 June 2021



Glider



Glider horizontal speed: 1.20 km/h

Glider depth range: from 1 to 50 metres from the surface

Surface time interval Every 3 hrs during daytime

Glider sensor sampling frequency: 10 seconds

Glider yo angle: 26 deg up and dow

Number of dives per waypoints 3

Surfacing time interval for communication 20 min

- CTD: temperature and salinity
- Fluorescence: chlorophyll
- Oxygen



Assimilation and forecast model



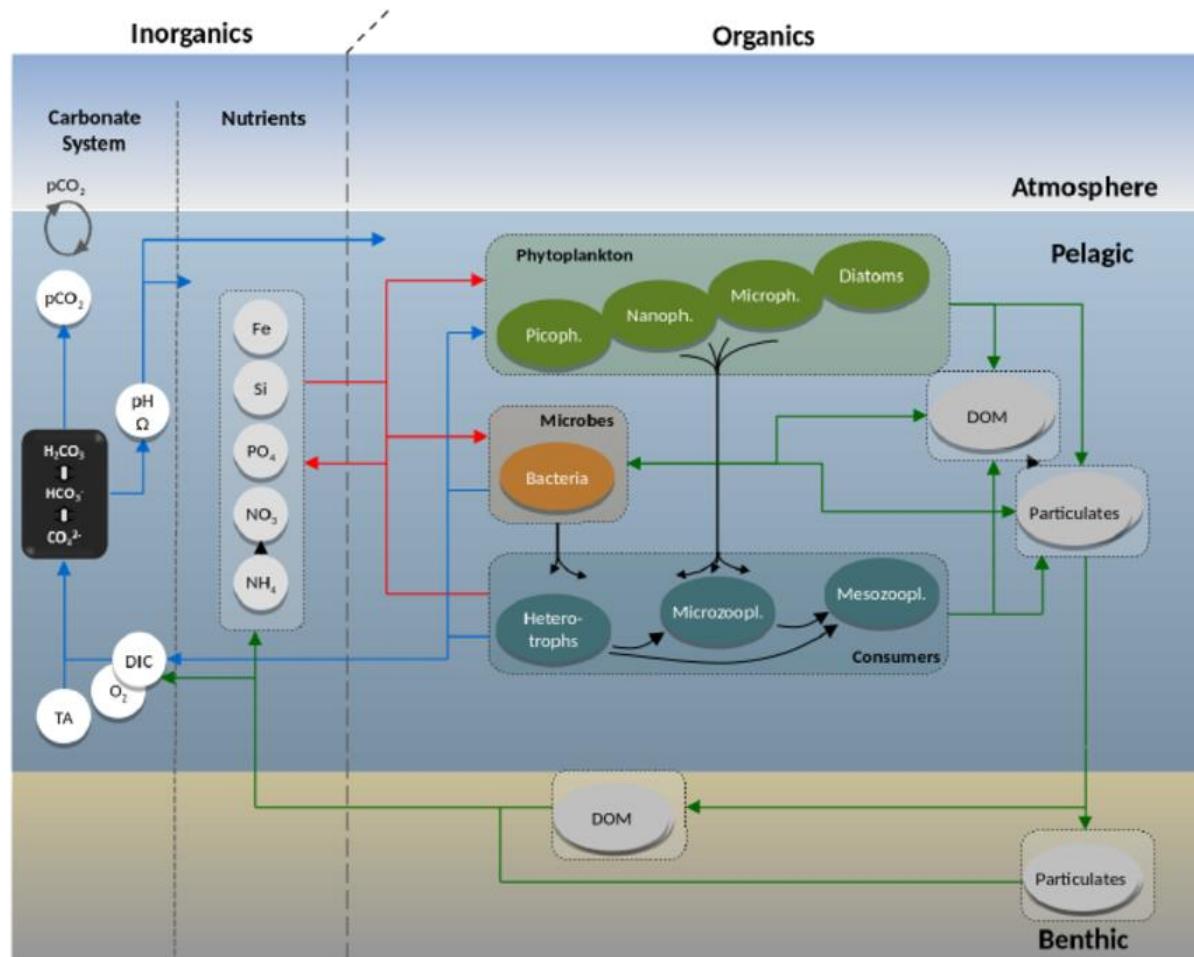


+

European Regional
Seas Ecosystem
Model (**ERSEM**)

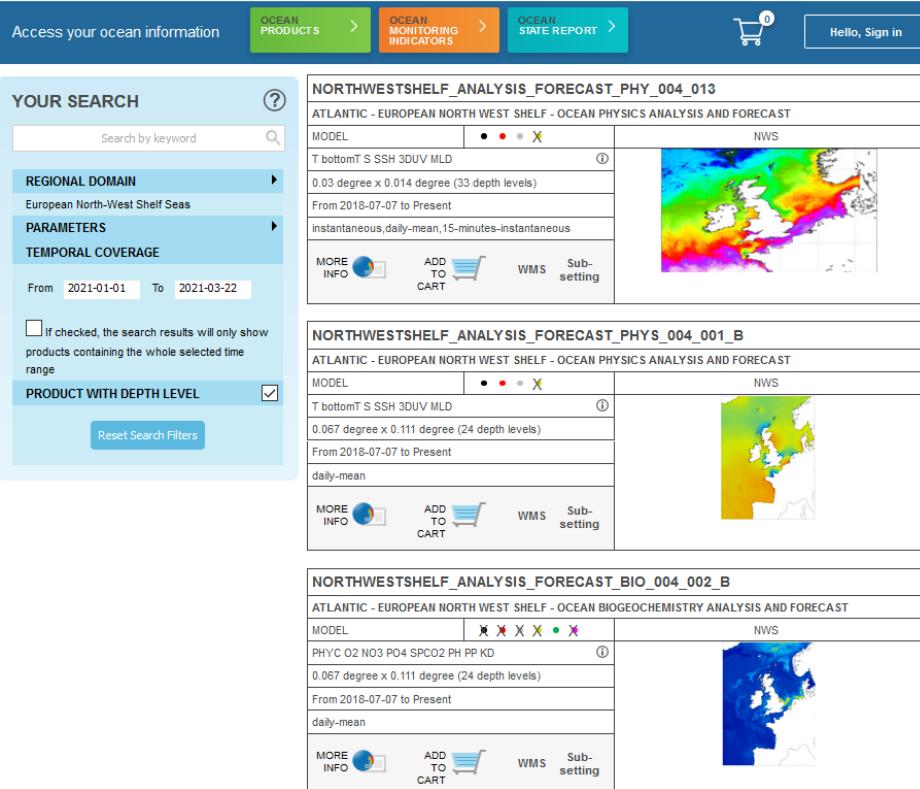
+

NEMOVAR
(3D-Var assimilation)



7km resolution

- Operational forecasts
 - Analysis and six-day forecast available from Copernicus Marine
 - Updated daily
- Physics assimilation:
 - Satellite and in situ SST
 - In situ temperature and salinity
 - Satellite altimetry
- Biogeochemistry assimilation:
 - Chlorophyll from satellite ocean colour



<https://marine.copernicus.eu/>

JGR Oceans

Research Article |  Open Access |  

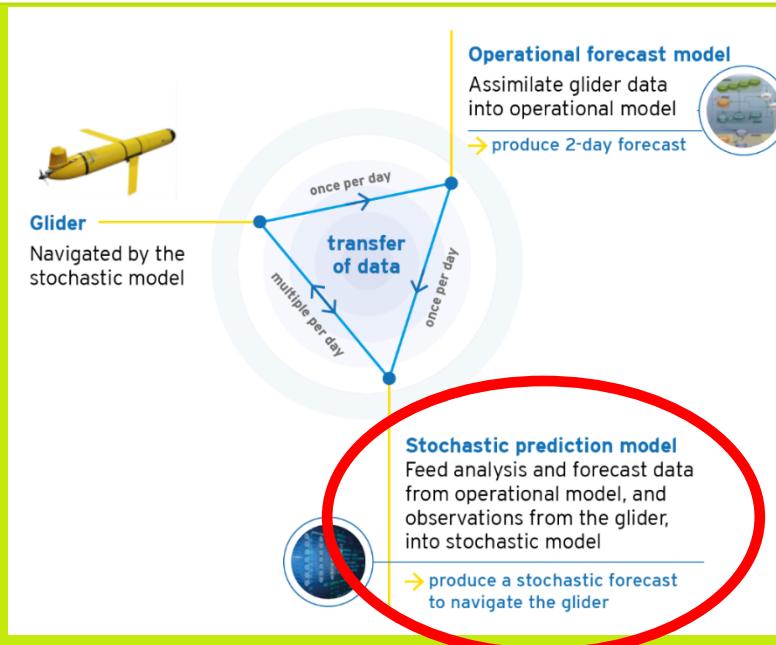
Towards a Multi-Platform Assimilative System for North Sea Biogeochemistry

Jozef Skákala✉, David Ford, Jorn Bruggeman, Tom Hull, Jan Kaiser, Robert R. King, Benjamin Loveday, Matthew R. Palmer, Tim Smyth, Charlotte A. J. Williams, Stefano Ciavatta

First published: 20 February 2021 | <https://doi.org/10.1029/2020JC016649> | Citations: 3

- Run daily at 09:00 UTC
- Identical to operational suite but assimilating the glider chlorophyll and oxygen data
- Hourly mean chlorophyll and temperature for past five days (analysis) and next six days (forecast) processed for glider region and placed on FTP

Stochastic model and path planning

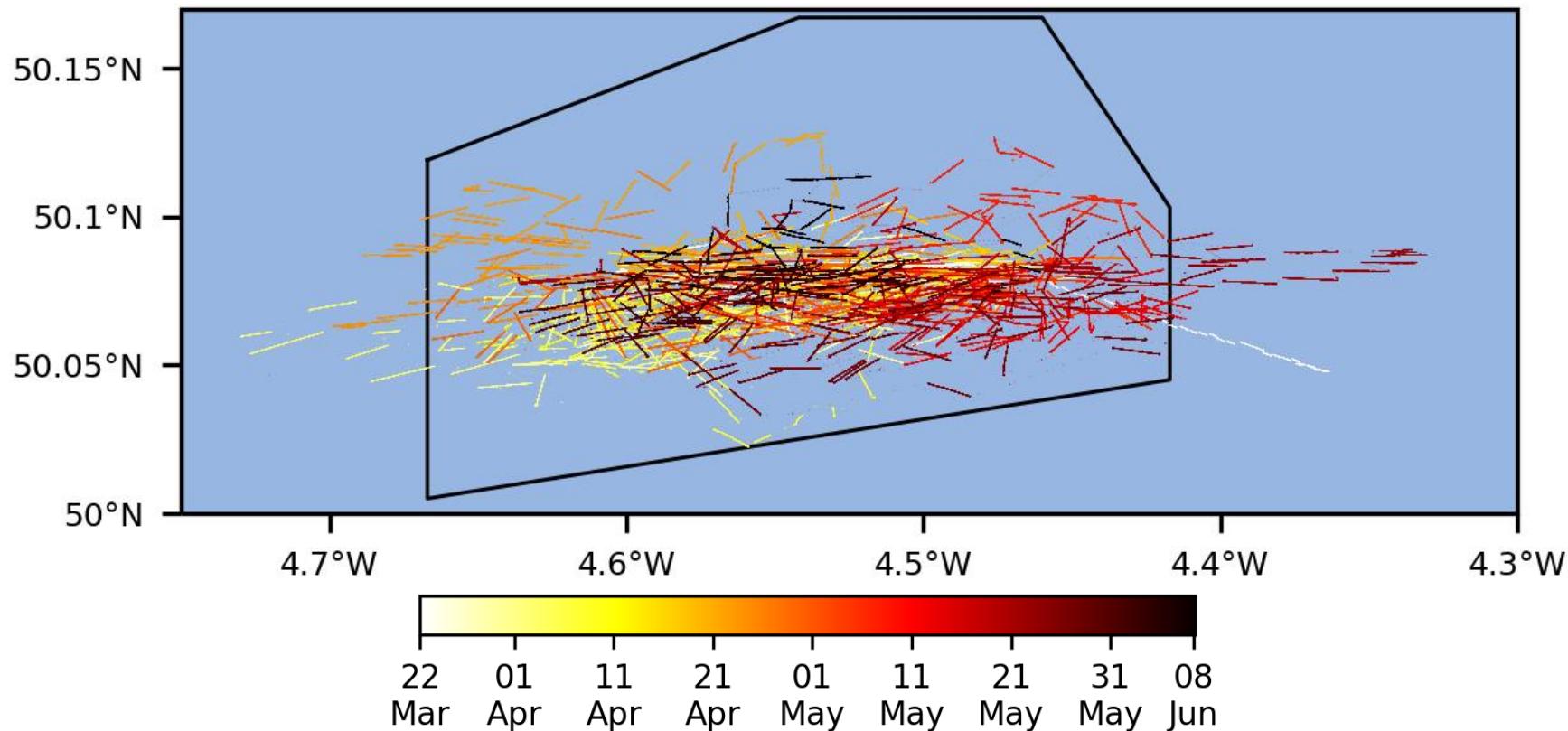


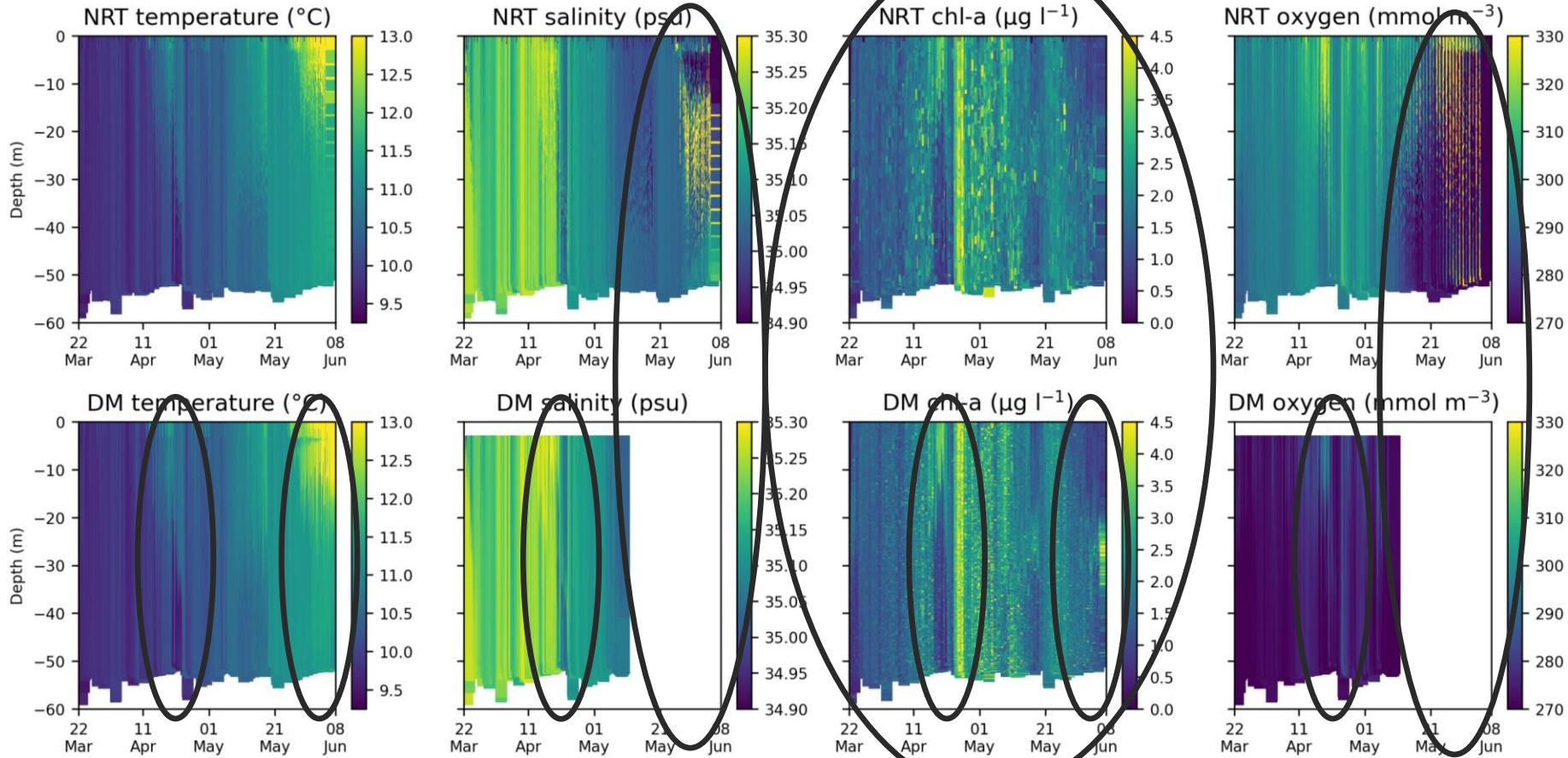
- Developed and run at University of Exeter
- Uses the integrated nested Laplace approximation (INLA) to approximate Bayesian inference (www.r-inla.org)
- Inputs:
 - Glider chlorophyll
 - Model chlorophyll and temperature
- Outputs:
 - High-resolution ($0.0014^\circ \times 0.0009^\circ$) 24-hour chlorophyll forecast
 - Sets of waypoints for the glider, automatically emailed to pilot, based on location of forecasted chlorophyll maximum

Results

Observations

Glider trajectory

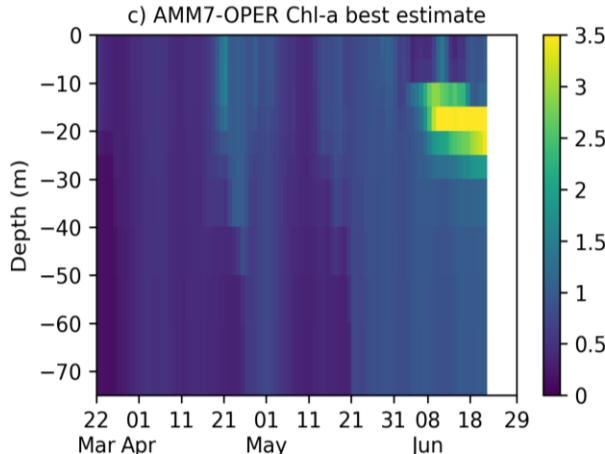




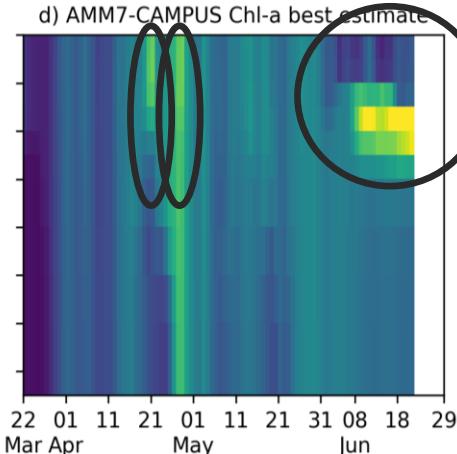
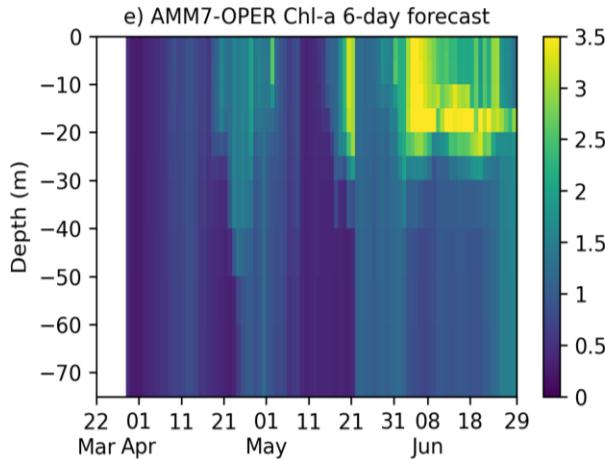
Results

Impact of glider assimilation on forecasts

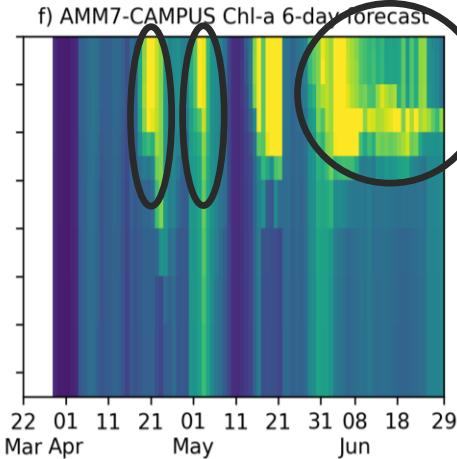
Chl-a analysis
without
glider assimilation



6-day forecast
without
glider assimilation



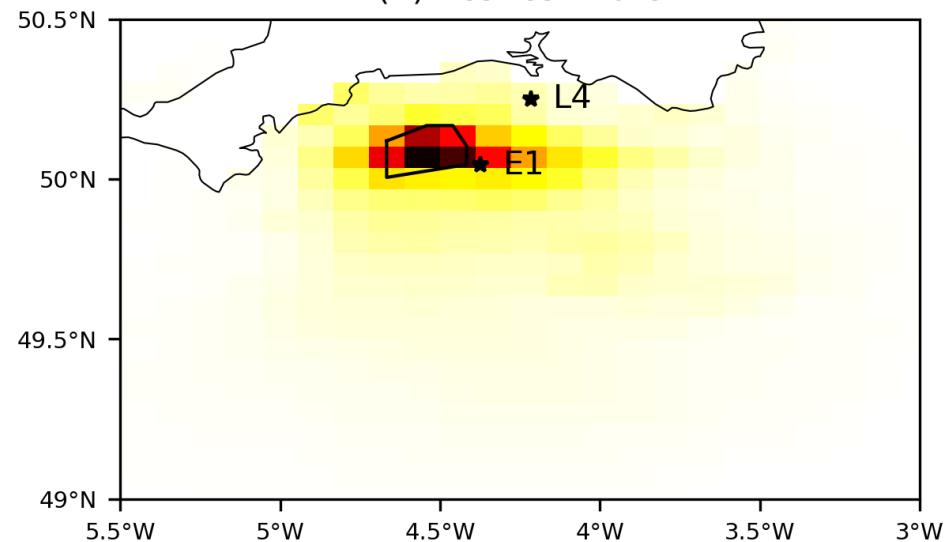
Chl-a analysis
with
glider assimilation



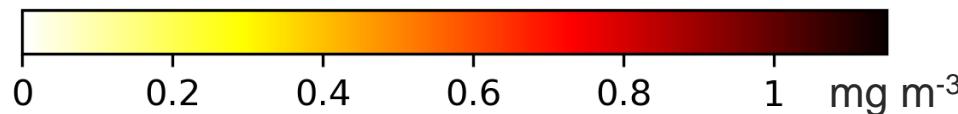
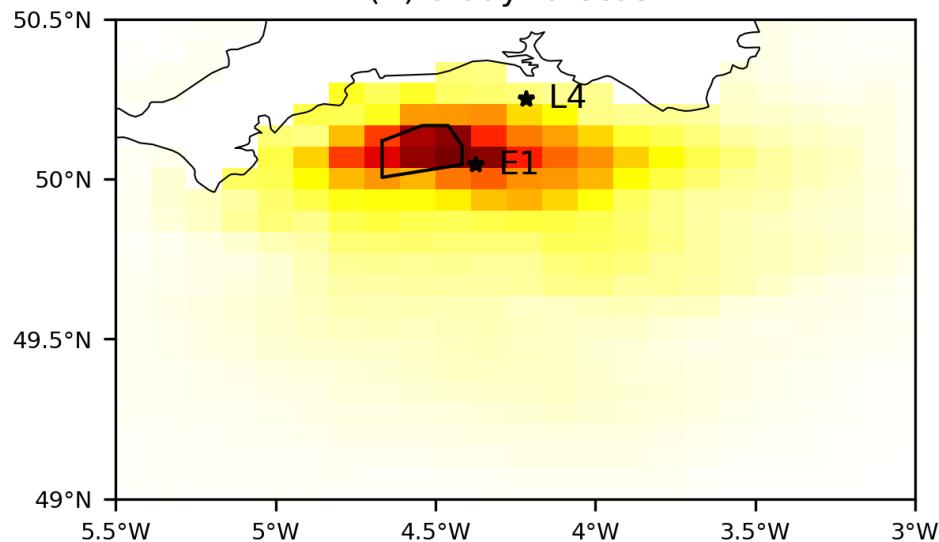
6-day forecast
with
glider assimilation

Mean absolute difference in surface chlorophyll with and without glider assimilation

(A) Best estimate



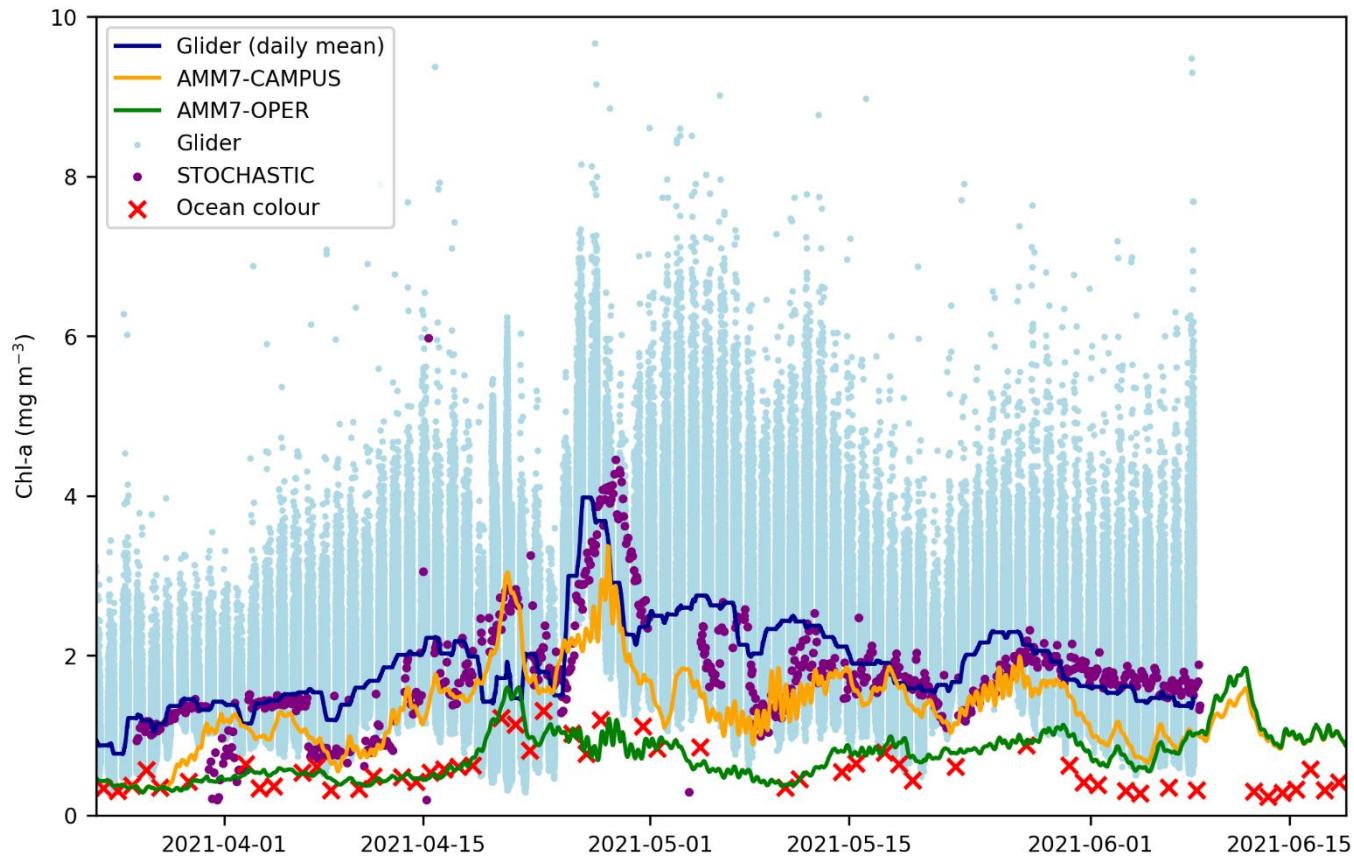
(B) 6-day forecast



Results

Intercomparison of observations and models

(Near-)surface chlorophyll

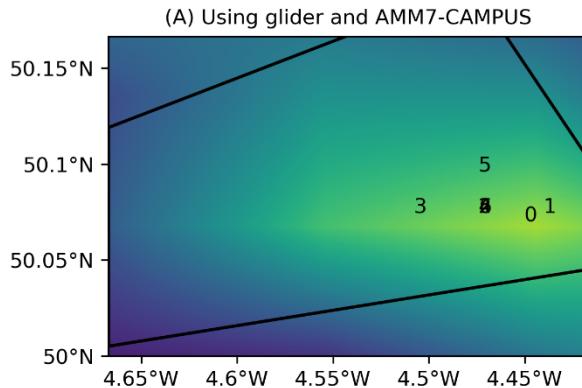


Results

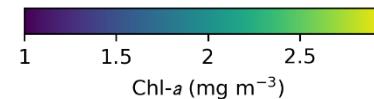
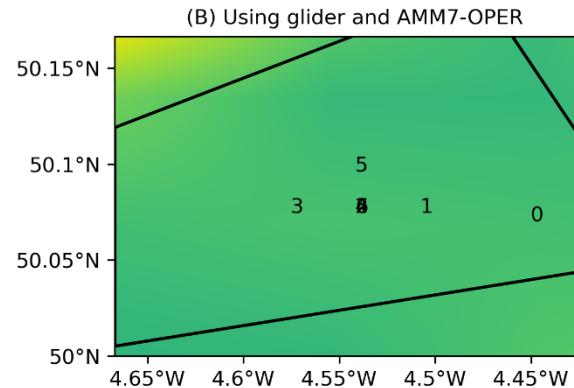
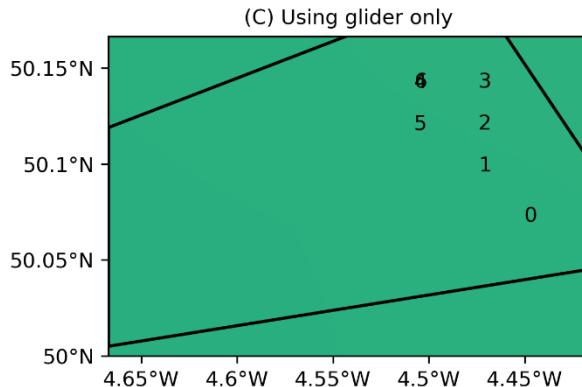
Sensitivity of stochastic model to inputs

Stochastic model chlorophyll forecast and waypoints 14 May 2021

Using
observations
and model
with glider
assimilation



Using
observations
only



Using
observations
and model
without glider
assimilation

Summary and future challenges

Summary

- Successful proof-of-concept of an autonomous and adaptive “smart” observing system integrating models and gliders
- Observations improve models and models improve observations

Future challenges

- Biofouling!
- Near-real time QC
- Multiple gliders and larger area
- Accounting for currents
- Regulations (e.g. requiring a human pilot)
- Reconciling differences between satellite and in situ data
- Ensure biases don't restrict trajectory
- Apply to other variables and observing platforms?

ORIGINAL RESEARCH article

Front. Mar. Sci., 19 December 2022

Sec. Ocean Observation

Volume 9 - 2022 | <https://doi.org/10.3389/fmars.2022.1067174>

A solution for autonomous, adaptive monitoring of coastal ocean ecosystems: Integrating ocean robots and operational forecasts

David A. Ford^{1*},Shenan Grossberg²,Gianmario Rinaldi²,Prathyush P. Menon²,Matthew R. Palmer^{3,4},Jozef Skákala^{4,5},Tim Smyth⁴, Charlotte A. J. Williams³,Alvaro Lorenzo Lopez⁶ and Stefano Ciavatta^{4,5,7}¹ Met Office, Exeter, United Kingdom² Faculty of Environment, Science and Economy, University of Exeter, Exeter, United Kingdom³ National Oceanography Centre, Liverpool, United Kingdom⁴ Plymouth Marine Laboratory, Plymouth, United Kingdom⁵ National Centre for Earth Observation, Plymouth, United Kingdom⁶ Marine Autonomous and Robotic Systems, National Oceanography Centre, Southampton, United Kingdom⁷ Mercator Océan International, Toulouse, France

Questions?